

Lecture 12

Signal Transmission & Windowing Effects (Lathi 7.4, 7.6, 7.8)

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Example

- Find the zero-state response of a stable LTI system with transfer function

$$H(s) = \frac{1}{s+2}$$

and the input is $x(t) = e^{-t}u(t)$.

- The FT of input $x(t)$ is: $X(\omega) = \frac{1}{j\omega + 1}$

- Since the system is stable, therefore $H(j\omega) = H(\omega)$. Hence

$$H(\omega) = H(s)|_{s=j\omega} = \frac{1}{j\omega + 2}$$

- Therefore $Y(\omega) = H(\omega)X(\omega) = \frac{1}{(j\omega + 2)(j\omega + 1)}$

- Using partial fractions, we get:

$$Y(\omega) = \frac{1}{j\omega + 1} - \frac{1}{j\omega + 2}$$

$$y(t) = (e^{-t} - e^{-2t})u(t)$$

L7.4 p717

Signal Transmission through LTI Systems

- We have seen previously that if $x(t)$ and $y(t)$ are input & output of a LTI system with impulse response $h(t)$, then

$$Y(\omega) = H(\omega)X(\omega)$$

- We can therefore perform LTI system analysis with Fourier transform in a way similar to that of Laplace transform.
- However, FT is more **restrictive** than Laplace transform because the system must be **stable**, and $x(t)$ must itself be Fourier transformable.
- Laplace transform can be used to analyse stable AND unstable system, and apply to signals that grow exponentially.
- If a system is stable, it can shown that the frequency response of the system $H(j\omega)$ is just the Fourier transform of $h(t)$ (i.e. $H(\omega)$):

$$H(\omega) = H(s)|_{s=j\omega}$$

L7.4 p717

Time-domain vs Frequency-domain

Impulse response

$$\delta(t) \Rightarrow h(t)$$

$x(t)$ as sum of impulse components

$$x(t) = \int_{-\infty}^{\infty} x(\tau)\delta(t - \tau) d\tau$$

$y(t)$ as sum of responses to impulse components

$$y(t) = \int_{-\infty}^{\infty} x(\tau)h(t - \tau) d\tau$$

System response to $e^{j\omega t}$ is $H(\omega)e^{j\omega t}$

$$e^{j\omega t} \Rightarrow H(\omega)e^{j\omega t}$$

$x(t)$ as sum of everlasting exponential components

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega)e^{j\omega t} d\omega$$

$y(t)$ as sum of responses to exponential components

$$y(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega)H(\omega)e^{j\omega t} d\omega$$

L7.4 p718

Signal Distortion during transmission

- QUESTION: What is the characteristic of a system that allows signal to pass without distortion?
- Transmission is distortionless if output is identical to input within a multiplicative constant, and relative delay is allowed. That is:

$$y(t) = G_0 x(t - t_d) \quad \longrightarrow \quad Y(\omega) = G_0 X(\omega) e^{-j\omega t_d}$$

- But $Y(\omega)/X(\omega) = H(\omega)$, therefore the frequency characteristic of a distortionless system is:

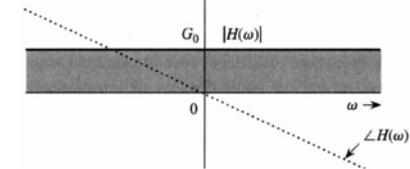
$$H(\omega) = G_0 e^{-j\omega t_d} \quad \begin{cases} |H(\omega)| = G_0 \\ \angle H(\omega) = -\omega t_d \end{cases}$$

For distortionless transmission, amplitude response $|H(\omega)|$ must be a constant AND phase response $\angle H(\omega)$ must be linear function of ω with slope $-t_d$.

L7.4 p720

Group Delay (again)

- $\angle H(\omega) = -\omega t_d$ means that **every** spectral component is delayed by t_d seconds.
- Therefore a distortionless transmission needs a **flat** amplitude response and a **linear** phase response:



- Measure phase linearity with:

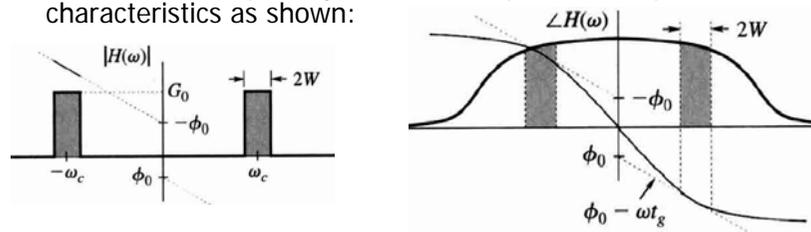
$$t_g(\omega) = -\frac{d}{d\omega} \angle H(\omega)$$

- If $t_g(\omega)$ is constant, signal is delayed by t_g (assuming constant $H(\omega)$).
- $t_g(\omega)$ is known as **Group delay** or **Envelope delay**.
- Human ears are sensitive to amplitude distortion, but not phase distortion.
- Human eyes are sensitive to phase distortion, but not (so much) amplitude distortion

L7.4 p721

Bandpass Systems & Group Delay

- Consider a bandpass system with amplitude and phase characteristics as shown:



- If one applies an input $z(t) = x(t) \cos \omega_c t$, then the output $y(t)$ is:

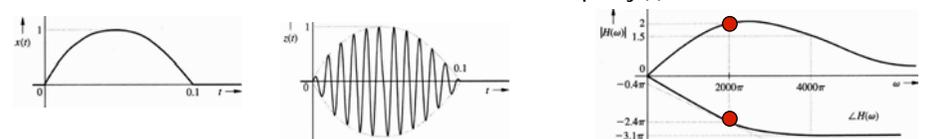
$$y(t) = G_0 x(t - t_g) \cos [\omega_c(t - t_g) + \phi_0]$$

- That is, the output is the delayed version of input $z(t)$ and the output carrier acquires an extra phase ϕ_0 .
- The envelope of the signal is therefore distortionless.
- For the proof, see Lathi page 723.

L7.4 p722

Example

- A signal $z(t)$ shown below is given by $z(t) = x(t) \cos \omega_c t$ where $\omega_c = 2000\pi$. The pulse $x(t)$ is a lowpass pulse of duration 0.1sec and has a bandwidth of about 10Hz. This signal is passed through a filter whose frequency response is shown below. Find and sketch the filter output $y(t)$.

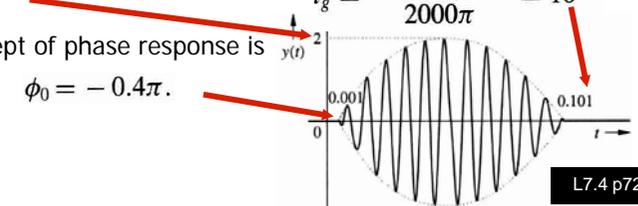


- $Z(t)$ is a narrow band signal with bandwidth of 20Hz centered around 1kHz.
- The gain at 1kHz is 2. The group delay is:

$$t_g = \frac{2.4\pi - 0.4\pi}{2000\pi} = 10^{-3}$$

- The vertical intercept of phase response is

$$\phi_0 = -0.4\pi$$



L7.4 p724

Parseval's Theorem

- The energy of a signal $x(t)$ can be derived in time or frequency domain:

$$E_x = \int_{-\infty}^{\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(\omega)|^2 d\omega$$

- Proof:

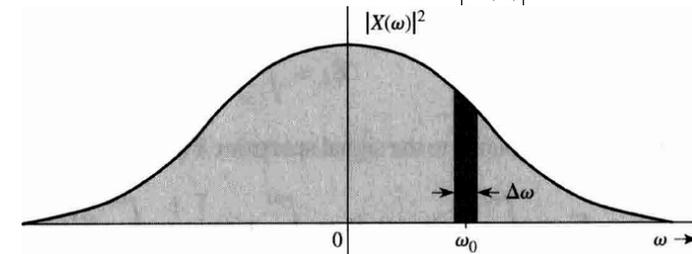
$$\begin{aligned} E_x &= \int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\infty}^{\infty} x(t)x^*(t) dt \\ &= \int_{-\infty}^{\infty} x(t) \left[\frac{1}{2\pi} \int_{-\infty}^{\infty} X^*(\omega)e^{-j\omega t} d\omega \right] dt \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} X^*(\omega) \left[\int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt \right] d\omega \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} X^*(\omega)X(\omega) d\omega \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(\omega)|^2 d\omega \end{aligned}$$

Change order of integration

L7.6 p730

Energy Spectral Density of a signal

- Total energy is area under the curve of $|X(\omega)|^2$ vs ω (divided by 2π).



- The energy over a small frequency band $\Delta\omega$ ($\Delta\omega \rightarrow 0$) is:

$$\Delta E_x = \frac{1}{2\pi} |X(\omega)|^2 \Delta\omega = |X(\omega)|^2 \Delta f \quad \frac{\Delta\omega}{2\pi} = \Delta f \text{ Hz}$$

Energy spectral density (per unit bandwidth in Hz)

L7.6 p730

Energy Spectral Density of a REAL signal

- If $x(t)$ is a real signal, then $X(\omega)$ and $X(-\omega)$ are conjugate (L11, slide2):

$$|X(\omega)|^2 = X(\omega)X^*(\omega) = X(\omega)X(-\omega)$$

- This implies that $X(\omega)$ is an even function. Therefore

$$E_x = \frac{1}{\pi} \int_0^{\infty} |X(\omega)|^2 d\omega$$

- Consequently, the energy contributed by a real signal by spectral components between ω_1 and ω_2 is:

$$\Delta E_x = \frac{1}{\pi} \int_{\omega_1}^{\omega_2} |X(\omega)|^2 d\omega$$

L7.6 p730

Example

- Find the energy E of signal $x(t) = e^{-at} u(t)$. Determine the frequency W (rad/s) so that the energy contributed by the spectral component from 0 to W is 95% of the total signal energy E .

- Take FT of $x(t)$:

$$X(\omega) = \frac{1}{j\omega + a}$$

- By Parseval's theorem:

$$E_x = \frac{1}{\pi} \int_0^{\infty} |X(\omega)|^2 d\omega = \frac{1}{\pi} \int_0^{\infty} \frac{1}{\omega^2 + a^2} d\omega = \frac{1}{\pi a} \tan^{-1} \frac{\omega}{a} \Big|_0^{\infty} = \frac{1}{2a}$$

- Energy in band 0 to W is 95% of this, therefore:

$$\frac{0.95}{2a} = \frac{1}{\pi} \int_0^W \frac{d\omega}{\omega^2 + a^2} = \frac{1}{\pi a} \tan^{-1} \frac{\omega}{a} \Big|_0^W = \frac{1}{\pi a} \tan^{-1} \frac{W}{a}$$

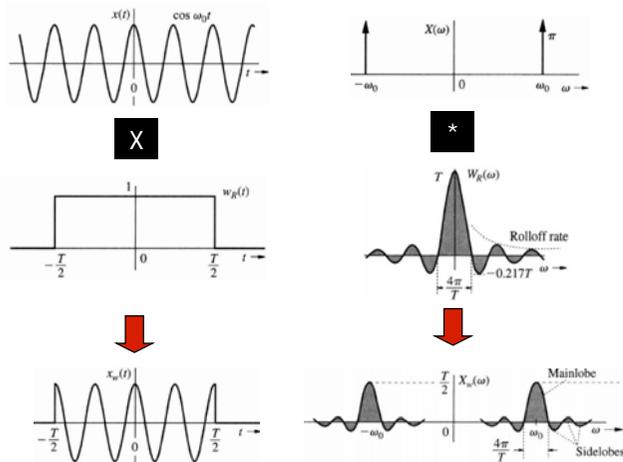
$$\frac{0.95\pi}{2} = \tan^{-1} \frac{W}{a} \implies W = 12.706a \text{ rad/s}$$

- Note: For this signal, 95% of energy is in small frequency band from 0 to 12.7a rad/s or 2.02a Hz!!!

L7.6 p731

Windowing and its effect

- Extracting a segment of a signal in time is the same as multiplying the signal with a rectangular window:



Spectral spreading

Energy spread out from ω_0 to width of $2\pi/T$ – reduced spectral resolution.

Leakage

Energy leaks out from the mainlobe to the sidelobes.

L7.8 p746

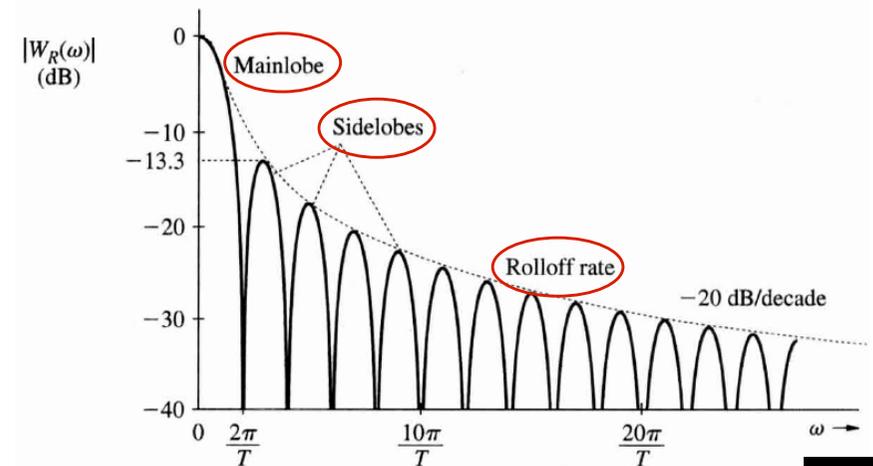
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Mainlobe & Sidelobes in dB

- Detail effects of windowing (rectangular window):



L7.8 p746

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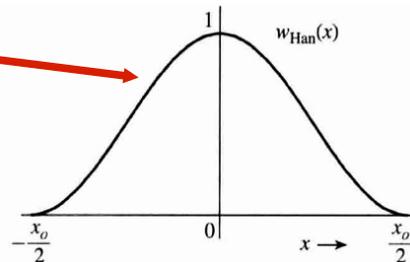
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Remedies for side effects of truncation

- Make mainlobe width as narrow as possible -> implies as wide a window as possible.
 - Avoid big discontinuity in the windowing function to reduce leakage (i.e. high frequency sidelobes).
 - 1) and 2) above are incompatible – therefore needs a compromise.
- Commonly used windows outside rectangular window are:

- Hamming windows
- Hanning windows
- Barlett windows
- Blackman windows
- Kaiser windows



L7.8 p746

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Comparison of different windowing functions

No.	Window $w(t)$	Mainlobe Width	Rolloff Rate (dB/oct)	Peak Sidelobe level (dB)
1	Rectangular: $\text{rect}\left(\frac{t}{T}\right)$	$\frac{4\pi}{T}$	-6	-13.3
2	Bartlett: $\Delta\left(\frac{t}{2T}\right)$	$\frac{8\pi}{T}$	-12	-26.5
3	Hanning: $0.5 \left[1 + \cos\left(\frac{2\pi t}{T}\right) \right]$	$\frac{8\pi}{T}$	-18	-31.5
4	Hamming: $0.54 + 0.46 \cos\left(\frac{2\pi t}{T}\right)$	$\frac{8\pi}{T}$	-6	-42.7
5	Blackman: $0.42 + 0.5 \cos\left(\frac{2\pi t}{T}\right) + 0.08 \cos\left(\frac{4\pi t}{T}\right)$	$\frac{12\pi}{T}$	-18	-58.1
6	Kaiser: $\frac{I_0\left[\alpha \sqrt{1 - 4\left(\frac{t}{T}\right)^2}\right]}{I_0(\alpha)}$ $0 \leq \alpha \leq 10$	$\frac{11.2\pi}{T}$	-6	-59.9 ($\alpha = 8.168$)

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